# Eye movement analysis with switching hidden Markov models: Appendix 

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## A. Derivation of Switching HMM

The switching HMM is an HMM with an additional high-level state sequence that selects the currently active transition matrix. Formally, at time $t$ for the $n$th sequence, let $z_{n, t}=$ $\{1, \cdots, K\}$ be the hidden-state variable, $s_{n, t}=\{1, \cdots, S\}$ be the high-level state variable, and $x_{n, t}$ be the observation. The high-level state variable and hidden state variable are both 1st-order Markov chains. The transition matrix for the hidden state variable $z_{n, t}$ depends on the current high-level state $s_{n, t}$,

$$
\begin{align*}
p\left(\mathbf{s}_{n}\right) & =p\left(s_{n, 1}\right) \prod_{t=2}^{\tau_{n}} p\left(s_{n, t} \mid s_{n, t-1}\right),  \tag{1}\\
p\left(\mathbf{z}_{n} \mid \mathbf{s}_{n}\right) & =p\left(z_{n, 1} \mid s_{n, 1}\right) \prod_{t=2}^{\tau_{n}} p\left(z_{n, t} \mid z_{n, t-1}, s_{n, t}\right) \tag{2}
\end{align*}
$$

where the individual probability distributions are

$$
\begin{array}{rlrl}
\text { initial high-level state: } & p\left(s_{n, 1}\right. & =j) & =\rho_{j} \\
\text { high-level transition probability: } & p\left(s_{n, t}=j^{\prime} \mid s_{n, t-1}\right. & =j)=b_{j, j^{\prime}} \\
\text { initial state: } & p\left(z_{n, 1}=k \mid s_{n, 1}=j\right)=\pi_{k}^{(j)} \\
\text { transition probability: } & p\left(z_{n, t}=k^{\prime} \mid z_{n, t-1}=k, s_{n, t}=j\right)=a_{k, k^{\prime}}^{(j)}
\end{array}
$$

Note that we will always use $j$ for the high-level state $(s)$, and $k$ for the lower hidden state $(z)$. In some cases, we may want to set $\rho_{1}=1$ and $\rho_{j}=0$ for $j \neq 1$, which will force the SHMM to always start in the same high-level state.

The emission densities are Gaussian, and only depend on the current lower hidden state (i.e., are shared among high-level states),

$$
\begin{equation*}
\text { observation likelihood: } \quad p\left(\mathbf{x}_{n, t} \mid z_{n, t}=k\right)=\mathcal{N}\left(\mathbf{x}_{n, t} \mid \boldsymbol{\mu}_{k}, \boldsymbol{\Lambda}_{k}^{-1}\right), \tag{7}
\end{equation*}
$$

where $\left(\boldsymbol{\mu}_{k}, \boldsymbol{\Lambda}_{k}\right)$ are the mean and precision matrix of a Gaussian.

Finally, the joint probability model is

$$
\begin{equation*}
p(\mathbf{X}, \mathbf{Z}, \mathbf{S})=\prod_{n=1}^{D}\left[p\left(s_{n, 1}\right) p\left(z_{n, 1} \mid s_{n, 1}\right) p\left(x_{n, 1} \mid z_{n, 1}\right) \prod_{t=2}^{\tau_{n}} p\left(s_{n, t} \mid s_{n, t-1}\right) p\left(z_{n, t} \mid z_{n, t-1}, s_{n, t}\right) p\left(x_{n, t} \mid z_{n, t}\right) .\right] \tag{8}
\end{equation*}
$$

## A. 1 Equivalence to standard HMM

The switching HMM can be turned into a standard HMM by combining the high-level state variable and hidden state variable into a single hidden state variable. This can be seen by looking at their joint distribution,

$$
\begin{align*}
p\left(\mathbf{z}_{n}, \mathbf{s}_{n}\right) & =p\left(\mathbf{z}_{n} \mid \mathbf{s}_{n}\right) p\left(\mathbf{s}_{n}\right)  \tag{9}\\
& =p\left(z_{n, 1} \mid s_{n, 1}\right) p\left(s_{n, 1}\right) \prod_{t=2}^{\tau_{n}} p\left(z_{n, t} \mid z_{n, t-1}, s_{n, t}\right) p\left(s_{n, t} \mid s_{n, t-1}\right)  \tag{10}\\
& =p\left(s_{n, 1}, z_{n, 1}\right) \prod_{t=2}^{\tau_{n}} p\left(s_{n, t}, z_{n, t} \mid s_{n, t-1}, z_{n, t-1}\right), \tag{11}
\end{align*}
$$

where

$$
\begin{array}{rrr}
\text { initial state: } & p\left(s_{n, 1}=j, z_{n, 1}=k\right)=\rho_{j} \pi_{k}^{(j)}, \\
\text { transition probability: } & p\left(s_{n, t}=j^{\prime}, z_{n, t}=k^{\prime} \mid s_{n, t-1}=j, z_{n, t-1}=k\right)=b_{j, j^{\prime}} a_{k, k^{\prime}}^{\left(j^{\prime}\right) .} \tag{13}
\end{array}
$$

Hence, an equivalent HMM can be formed by defining an augmented set of hidden states $\tilde{z}_{n, t}$ that takes a state value pair $(j, k)$, where $j$ is the high-level state and $k$ is the low-level hidden state. The transition matrix and initial state probability take a special form,

$$
\begin{align*}
p\left(\tilde{z}_{n, t}=\left(j^{\prime}, k^{\prime}\right) \mid \tilde{z}_{n, t-1}\right. & =(j, k))=\tilde{a}_{(j, k),\left(j^{\prime}, k^{\prime}\right)}=b_{j, j^{\prime}} a_{k, k^{\prime}}^{\left(j^{\prime}\right)},  \tag{14}\\
p\left(\tilde{z}_{n, 1}\right. & =(j, k))=\tilde{\pi}_{(j, k)}=\rho_{j} \pi_{k}^{(j)} . \tag{15}
\end{align*}
$$

Note that this is equivalent to defining an HMM with $S K$ hidden states, where the pair $(j, k)$ is mapped to a single index via $k=k+(j-1) S$. The transition matrix is a block matrix

$$
\tilde{\mathbf{A}}=\left[\begin{array}{ccc}
b_{1,1} \mathbf{A}^{(1)} & b_{1,2} \mathbf{A}^{(2)} & \ldots  \tag{16}\\
b_{2,1} \mathbf{A}^{(1)} & b_{2,2} \mathbf{A}^{(2)} & \ldots \\
\vdots & \vdots & \ddots
\end{array}\right]
$$

where $\mathbf{A}^{(j)}=\left[a_{k, k^{\prime}}^{(j)}\right]_{k, k^{\prime}}$ is the transition matrix for high-level state $j$, and the initial state probabilities are

$$
\tilde{\boldsymbol{\pi}}=\left[\begin{array}{c}
\rho_{1} \boldsymbol{\pi}^{(1)}  \tag{17}\\
\rho_{2} \boldsymbol{\pi}^{(2)} \\
\vdots
\end{array}\right]
$$

where $\boldsymbol{\pi}^{(j)}=\left[\pi_{1}^{(j)}, \cdots, \pi_{K}^{(j)}\right]^{T}$ is the prior state probability vector for high-level state $j$.
Finally, the Gaussian emissions are shared among high-levle states, i.e., do not depend on the high-level level state value $j$,

$$
\begin{equation*}
p\left(\mathbf{x}_{n, t} \mid \tilde{z}_{n, t}=(j, k)\right)=\mathcal{N}\left(\mathbf{x}_{n, t} \mid \boldsymbol{\mu}_{k}, \boldsymbol{\Lambda}_{k}^{-1}\right) \tag{18}
\end{equation*}
$$

## A. 2 Parameter estimation with EM

The SHMM parameters can be estimated by modifying the EM algorithm for HMMs. Here we drop the tilde notation for $z$ to reduce clutter. Define the indicator variables $z_{n, t,(j, k)}$ which is 1 if and only if $z_{n, t}=(j, k)$.

## A.2.1 Complete data likelihood and $\mathcal{Q}$ function

Using the indicator variable trick, the complete data log-likelihood is

$$
\begin{align*}
\log p(\mathbf{X}, \mathbf{Z})= & \log p(\mathbf{Z})+\log p(\mathbf{X} \mid \mathbf{Z})  \tag{19}\\
= & \sum_{n=1}^{N}\left[\log p\left(z_{n, 1}\right)+\sum_{t=2}^{\tau} \log p\left(z_{n, t} \mid z_{n, t-1}\right)+\sum_{t=1}^{\tau} \log p\left(\mathbf{x}_{n, t} \mid z_{n, t}\right)\right]  \tag{20}\\
= & \sum_{n=1}^{N}\left[\sum_{(j, k)} z_{n, 1,(j, k)} \log \tilde{\pi}_{(j, k)}+\sum_{t=2}^{\tau} \sum_{(j, k)} \sum_{\left(j^{\prime}, k^{\prime}\right)} z_{n, t,\left(j^{\prime}, k^{\prime}\right)} z_{n, t-1,(j, k)} \log \tilde{a}_{(j, k),\left(j^{\prime}, k^{\prime}\right)}\right. \\
& \left.+\sum_{t=1}^{\tau} \sum_{(j, k)} z_{n, t,(j, k)} \log p\left(\mathbf{x}_{n, t} \mid z_{n, t}=(j, k)\right)\right] \tag{21}
\end{align*}
$$

Taking the conditional expectation, we obtain the $\mathcal{Q}$ function for the EM algorithm,

$$
\begin{align*}
\mathcal{Q} & =\sum_{n=1}^{N} \sum_{(j, k)} r_{n, 1,(j, k)} \log \tilde{\pi}_{(j, k)}+\sum_{n=1}^{N} \sum_{t=2}^{\tau} \sum_{(j, k)} \sum_{\left(j^{\prime}, k^{\prime}\right)} \gamma_{n, t,(j, k),\left(j^{\prime}, k^{\prime}\right)} \log \tilde{a}_{(j, k),\left(j^{\prime}, k^{\prime}\right)} \\
& +\sum_{n=1}^{N} \sum_{t=1}^{\tau} \sum_{(j, k)} r_{n, t,(j, k)} \log p\left(\mathbf{x}_{n, t} \mid z_{n, t}=(j, k)\right) \tag{22}
\end{align*}
$$

where $r_{n, t,(j, k)}$ is the responsibility of observing the Gaussian for state $(j, k)$, and $\gamma_{n, t,(j, k),\left(j^{\prime}, k^{\prime}\right)}$ is the transition responsibility between $(j, k)$ to $\left(j^{\prime}, k^{\prime}\right)$,

$$
\begin{align*}
r_{n, t,(j, k)} & =\mathbb{E}_{z_{n, t} \mid \mathbf{X}}\left[z_{n, t,(j, k)}\right]=p\left(z_{n, t}=(j, k) \mid \mathbf{X}\right)  \tag{23}\\
\gamma_{n, t,(j, k),\left(j^{\prime}, k^{\prime}\right)} & =\mathbb{E}_{z_{n, t}, z_{n, t-1} \mid \mathbf{X}}\left[z_{n, t-1,(j, k)} z_{n, t,\left(j^{\prime}, k^{\prime}\right)}\right]=p\left(z_{n, t-1}=(j, k), z_{n, t}=\left(j^{\prime}, k^{\prime}\right) \mid \mathbf{X}\right) \tag{24}
\end{align*}
$$

## A.2.2 E-STEP

In the E-step, the responsibilities in (23) and (24) are calculated using the standard forwardbackward algorithm for HMMs with the augmented transition matrix, initial state vector, and emission densities given in (16), (17), and (18).

## A.2.3 M-Step

The M-step is similar to standard HMMs, except now we need to consider that the parameters have a particular form to make it equivalent to an SHMM.

Looking at the prior term in the $\mathcal{Q}$ function,

$$
\begin{align*}
\mathcal{Q} & =\sum_{n=1}^{N} \sum_{(j, k)} r_{n, 1,(j, k)} \log \tilde{\pi}_{(j, k)}=\sum_{n=1}^{N} \sum_{(j, k)} r_{n, 1,(j, k)} \log \rho_{j} \pi_{k}^{(j)}  \tag{25}\\
& =\sum_{n=1}^{N} \sum_{(j, k)} r_{n, 1,(j, k)} \log \rho_{j}+\sum_{n=1}^{N} \sum_{(j, k)} r_{n, 1,(j, k)} \log \pi_{k}^{(j)}  \tag{26}\\
& =\sum_{j}\left(\sum_{n=1}^{N} \sum_{k} r_{n, 1,(j, k)}\right) \log \rho_{j}+\sum_{j} \sum_{k}\left(\sum_{n=1}^{N} r_{n, 1,(j, k)}\right) \log \pi_{k}^{(j)} . \tag{27}
\end{align*}
$$

Define the summed responsibilities,

$$
\begin{align*}
N_{1,(j, k)} & =\sum_{n=1}^{N} r_{n, 1,(j, k)},  \tag{28}\\
L_{1, j} & =\sum_{n=1}^{N} \sum_{k=1}^{K} r_{n, 1,(j, k)}=\sum_{k=1}^{K} N_{1,(j, k)} . \tag{29}
\end{align*}
$$

Maximizing with respect to $\rho_{j}$ and $\pi_{k}^{(j)}$, and noting that they must sum to 1 (over $j$ and $k$ respectively), yields the parameter updates,

$$
\begin{align*}
\rho_{j} & =\frac{L_{1, j}}{\sum_{j^{\prime}=1}^{S} L_{1, j^{\prime}}},  \tag{30}\\
\pi_{k}^{(j)} & =\frac{N_{1,(j, k)}}{\sum_{k^{\prime}=1}^{K} N_{1,\left(j, k^{\prime}\right)}}=\frac{N_{1,(j, k)}}{L_{1, j}} . \tag{31}
\end{align*}
$$

Looking at the transition matrix in the $\mathcal{Q}$ function,

$$
\begin{align*}
\mathcal{Q} & =\sum_{n=1}^{N} \sum_{t=2}^{\tau} \sum_{(j, k)} \sum_{\left(j^{\prime}, k^{\prime}\right)} \gamma_{n, t,(j, k),\left(j^{\prime}, k^{\prime}\right)} \log \tilde{a}_{(j, k),\left(j^{\prime}, k^{\prime}\right)}  \tag{32}\\
& =\sum_{n=1}^{N} \sum_{t=2}^{\tau} \sum_{(j, k)} \sum_{\left(j^{\prime}, k^{\prime}\right)} \gamma_{n, t,(j, k),\left(j^{\prime}, k^{\prime}\right)} \log b_{j, j^{\prime}} a_{k, k^{\prime}}^{\left(j^{\prime}\right)}  \tag{33}\\
& =\sum_{n=1}^{N} \sum_{t=2}^{\tau} \sum_{(j, k)} \sum_{\left(j^{\prime}, k^{\prime}\right)} \gamma_{n, t,(j, k),\left(j^{\prime}, k^{\prime}\right)} \log b_{j, j^{\prime}}+\sum_{n=1}^{N} \sum_{t=2}^{\tau} \sum_{(j, k)} \sum_{\left(j^{\prime}, k^{\prime}\right)} \gamma_{n, t,(j, k),\left(j^{\prime}, k^{\prime}\right)} \log a_{k, k^{\prime}}^{\left(j^{\prime}\right)}  \tag{34}\\
& =\sum_{j} \sum_{j^{\prime}}\left(\sum_{n=1}^{N} \sum_{t=2}^{\tau} \sum_{k} \sum_{k^{\prime}} \gamma_{n, t,(j, k),\left(j^{\prime}, k^{\prime}\right)}\right) \log b_{j, j^{\prime}}+\sum_{j^{\prime}} \sum_{k} \sum_{k^{\prime}}\left(\sum_{n=1}^{N} \sum_{t=2}^{\tau} \sum_{j} \gamma_{n, t,(j, k),\left(j^{\prime}, k^{\prime}\right)}\right) \log a_{k, k^{\prime}}^{\left(j^{\prime}\right)} \tag{35}
\end{align*}
$$

Define the summed responsibilities,

$$
\begin{align*}
O_{j, j^{\prime}} & =\sum_{n=1}^{N} \sum_{t=2}^{\tau} \sum_{k=1}^{K} \sum_{k^{\prime}=1}^{K} \gamma_{n, t,(j, k),\left(j^{\prime}, k^{\prime}\right)},  \tag{36}\\
M_{k,\left(j^{\prime}, k^{\prime}\right)} & =\sum_{n=1}^{N} \sum_{t=2}^{\tau} \sum_{j=1}^{S} \gamma_{n, t,(j, k),\left(j^{\prime}, k^{\prime}\right)} . \tag{37}
\end{align*}
$$

Maximizing the $\mathcal{Q}$ function w.r.t. the parameters gives

$$
\begin{align*}
b_{j, j^{\prime}} & =\frac{O_{j, j^{\prime}}}{\sum_{l=1}^{S} O_{j, l}}  \tag{38}\\
a_{k, k^{\prime}}^{\left(j^{\prime}\right)} & =\frac{M_{k,\left(j^{\prime}, k^{\prime}\right)}}{\sum_{l=1}^{K} M_{k,\left(j^{\prime}, l\right)}} \tag{39}
\end{align*}
$$

Looking at the Gaussian term in the $\mathcal{Q}$ function,

$$
\begin{align*}
\mathcal{Q} & =\sum_{n=1}^{N} \sum_{t=1}^{\tau} \sum_{(j, k)} r_{n, t,(j, k)} \log p\left(\mathbf{x}_{n, t} \mid z_{n, t}=(j, k)\right)  \tag{40}\\
& =\sum_{n=1}^{N} \sum_{t=1}^{\tau} \sum_{(j, k)} r_{n, t,(j, k)} \mathcal{N}\left(\mathbf{x}_{n, t} \mid \boldsymbol{\mu}_{k}, \boldsymbol{\Lambda}_{k}^{-1}\right)  \tag{41}\\
& =\sum_{k} \sum_{n=1}^{N} \sum_{t=1}^{\tau}\left(\sum_{j} r_{n, t,(j, k)}\right) \mathcal{N}\left(\mathbf{x}_{n, t} \mid \boldsymbol{\mu}_{k}, \boldsymbol{\Lambda}_{k}^{-1}\right) \tag{42}
\end{align*}
$$

which is the same form as standard HMM but with the responsibilities summed over $j$ first. Defining

$$
\begin{align*}
\hat{r}_{n, t, k} & =\sum_{j=1}^{S} r_{n, t,(j, k)}  \tag{43}\\
N_{k} & =\sum_{n=1}^{N} \sum_{t=1}^{\tau} \hat{r}_{n, t, k} \tag{44}
\end{align*}
$$

the parameter updates are

$$
\begin{align*}
\boldsymbol{\mu}_{k} & =\frac{1}{N_{k}} \sum_{n=1}^{N} \sum_{t=1}^{\tau} \hat{r}_{n, t, k} \mathbf{x}_{n, t}  \tag{45}\\
\boldsymbol{\Lambda}_{k}^{-1} & =\frac{1}{N_{k}} \sum_{n=1}^{N} \sum_{t=1}^{\tau} \hat{r}_{n, t, k}\left(\mathbf{x}_{n, t}-\boldsymbol{\mu}_{k}\right)\left(\mathbf{x}_{n, t}-\boldsymbol{\mu}_{k}\right)^{T} \tag{46}
\end{align*}
$$

